

# WCRT for Synchronous Programs: Studying the Tick Alignment Problem

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# Structure of Talk

1. Motivation
2. Synchronous Multi-threading
3. Tick Cost Automata (TCA) and the Tick Alignment Problem (TAP)
4. Algorithms for TAP
5. Conclusion



# 1 MOTIVATION

# Emerging Trade on Synchronous WCRT

- (1) **Explicit Flow Traversal** [Boldt et.al. SLA++P'07, Mendler et.al. DATE'09] (Plus-Max Technique)
  - efficient (linear: sum of thread states), but large overestimates
- (2) **Implicit Path Enumeration** [Ju et.al. DAC'09, RTS'12]
  - exact ILP constraint solving, NP-hard
- (3) **Model Checking** [Roop et.al. CASES'09]
  - exact (exponential: product of thread states + binary search)
- (4) **State Exploration** [Kuo et.al. DAC'11, Yip et.al. ICCPS'13]
  - exact (exponential: product of thread states)
- (5) **(Iterative) Narrowing** [Wang et.al. CASES'13, Raymond et.al. RePP'14]
  - (i) get WCRT approximation; (ii) validate critical path in exact model; (iii) if infeasible, narrow WCRT approximation; repeat.
- (6) **High-level Flow Facts** [Raymond et.al. RePP'14]

# Emerging Trade on Synchronous WCRT

- ... shall we continue to develop
  - WCRT using **general purpose algorithms** (ILP, SAT, ...)
  - for **particular** SP languages and **particular** PRET architectures ?
- ... or, is there any systematics behind this work?
  - **common benchmark** suites to compare results ?
  - results on **algorithmic complexity** of WCRT ?
  - is there a **canonical WCRT Problem** ?

# WCRT Analysis: A Many-faceted Problem

- Data-dependent control path sensitization
- Thread preemption contexts

- Bus synchronisation and

- C

- M

- Int

- Sci

- ...

What if we abstract from all these complications?

**Q:** Does WCRT become trivial?

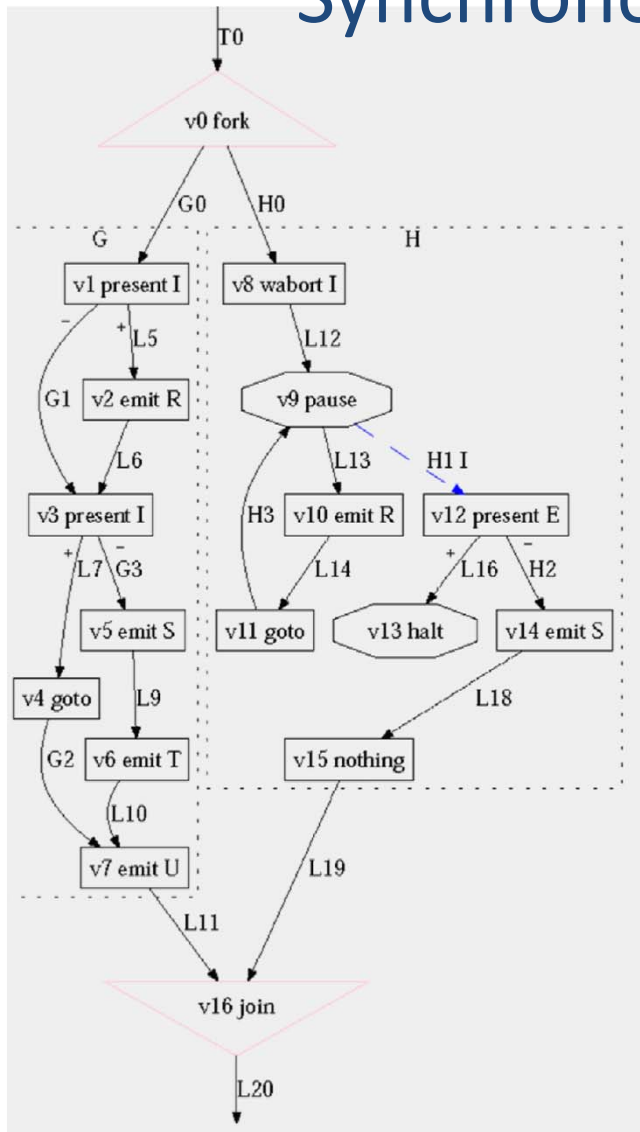
**A:** Open Problem ...



# 2

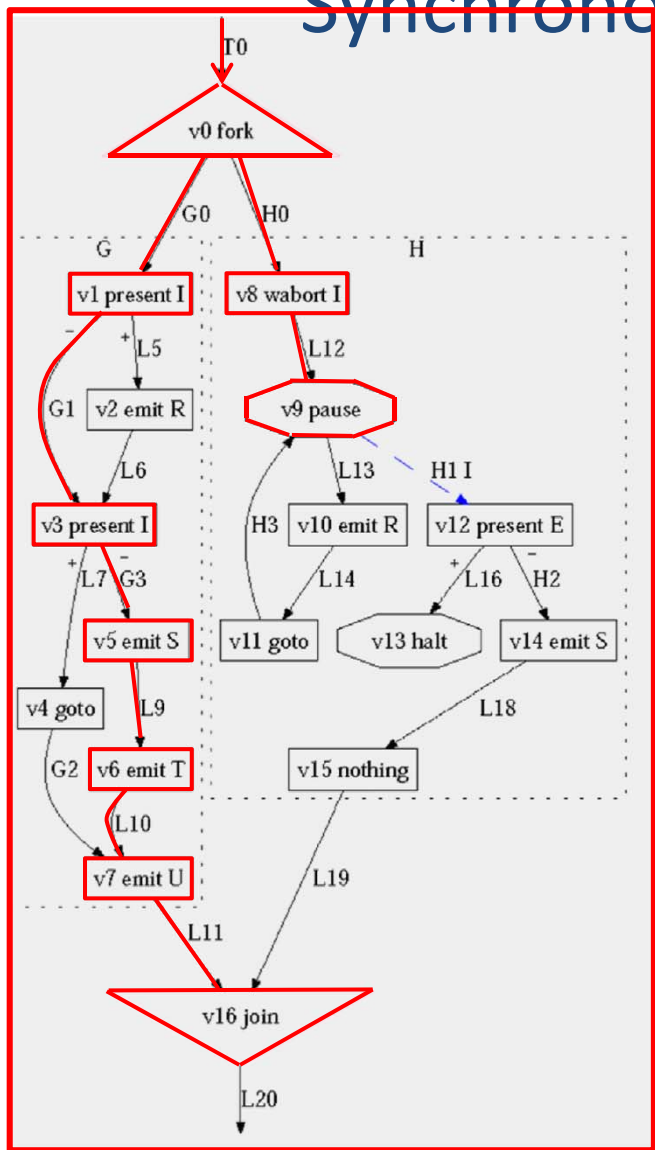
# SYNCHRONOUS MULTI-THREADING

# Synchronous Multi-Threading



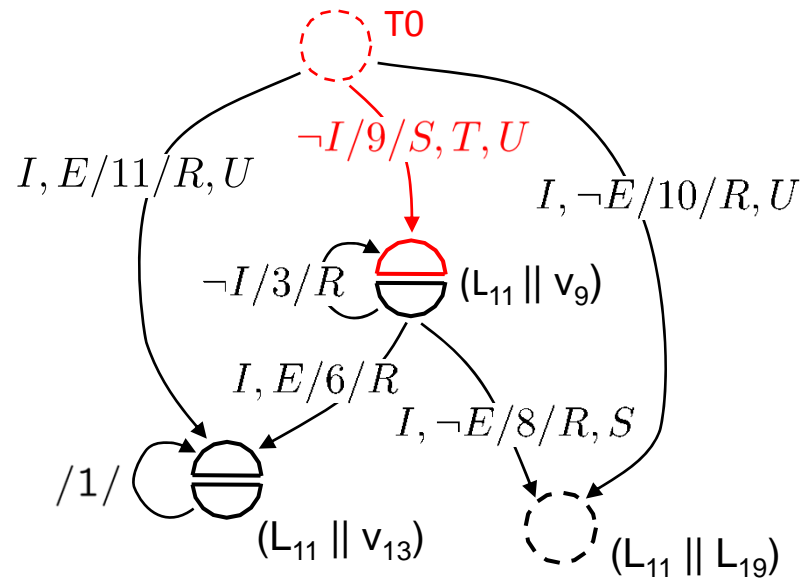


# Synchronous Multi-Threading

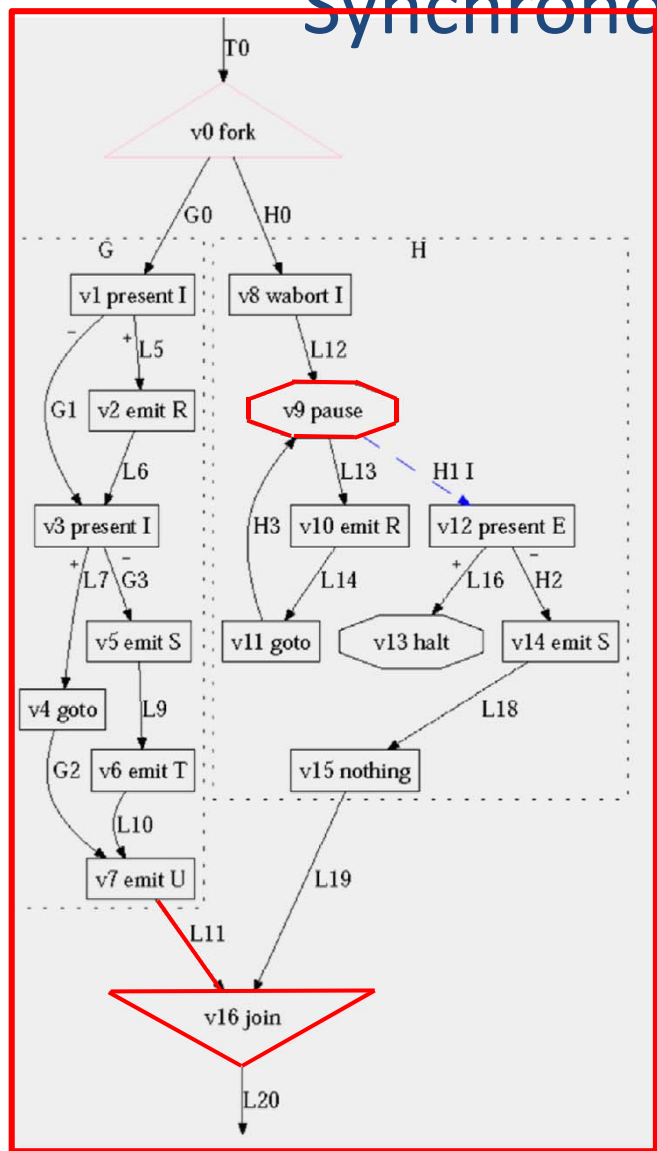


instantaneous entry  
 9 instruction cycles  
 pause

I absent  
 S,T,U emitted

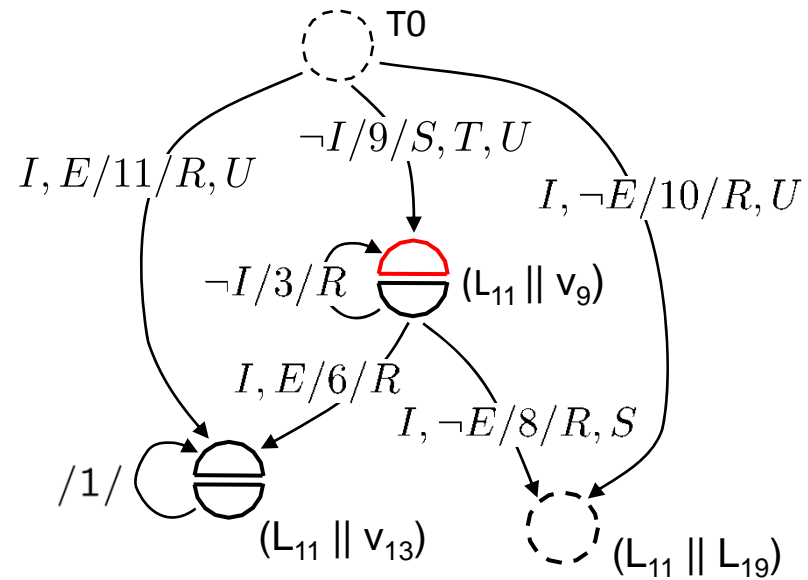


# Synchronous Multi-Threading

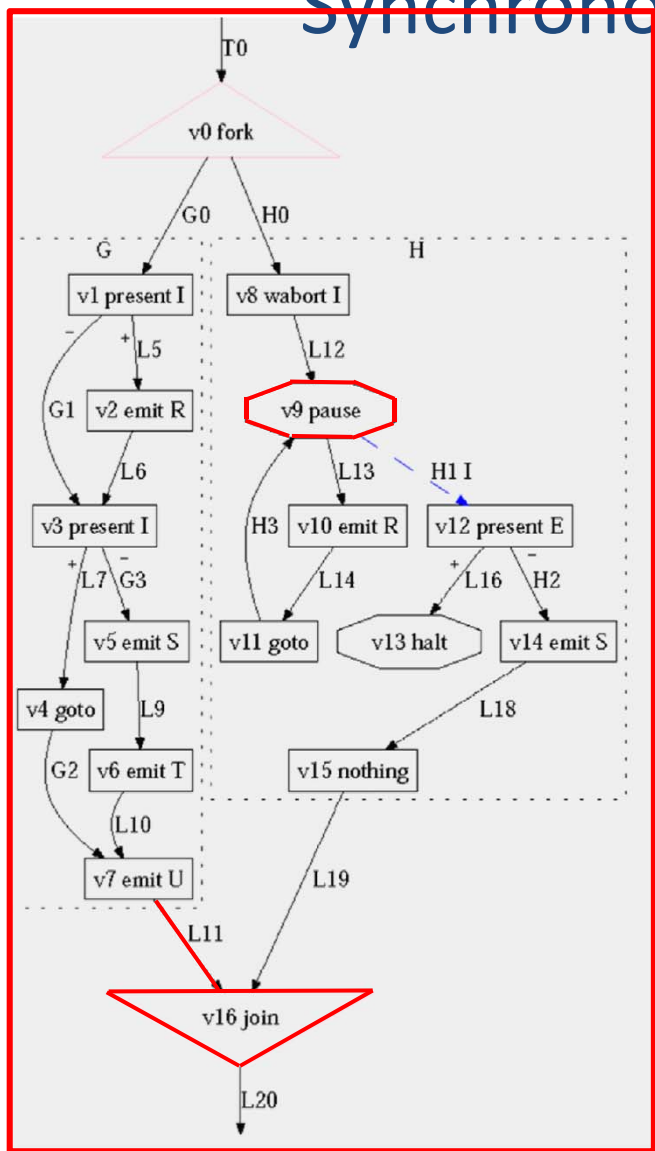


← instantaneous entry  
 9 instruction cycles  
 → pause

I absent  
 S,T,U emitted

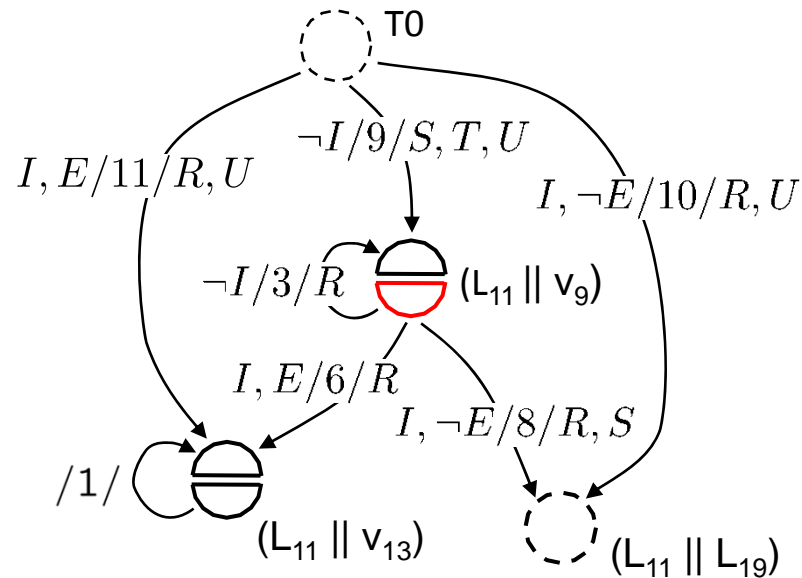


# Synchronous Multi-Threading

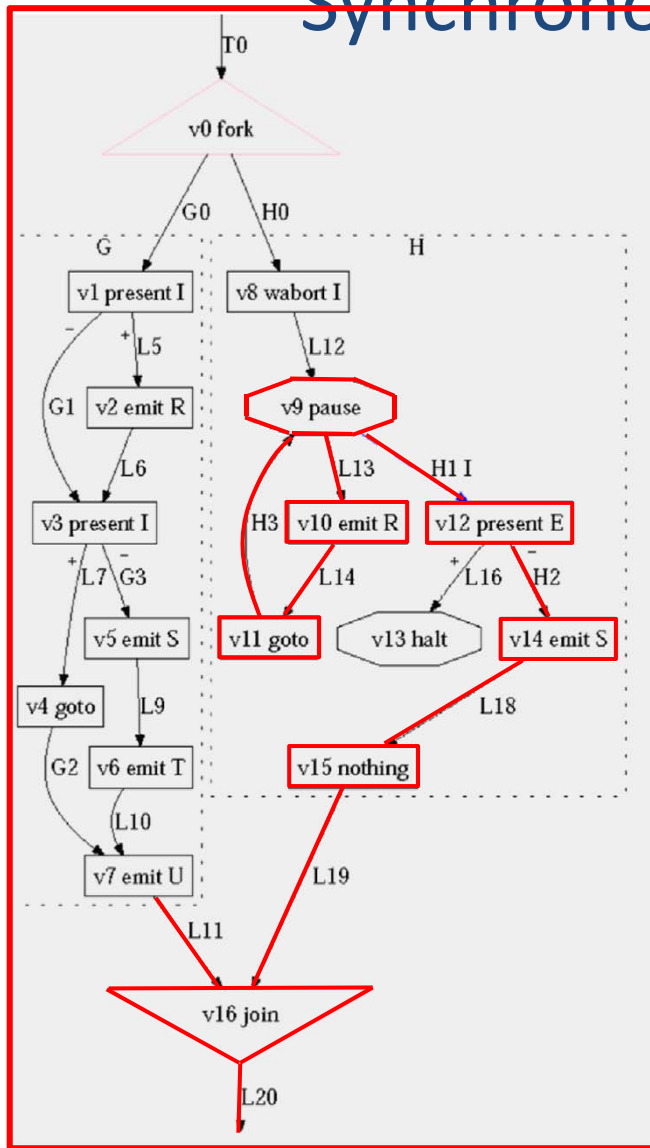


← instantaneous entry  
- - - - -> pause  
← tick

I absent  
 S,T,U emitted  
 I present, E absent



# Synchronous Multi-Threading



← instantaneous entry

I absent

9 instruction cycles

→ pause

S,T,U emitted

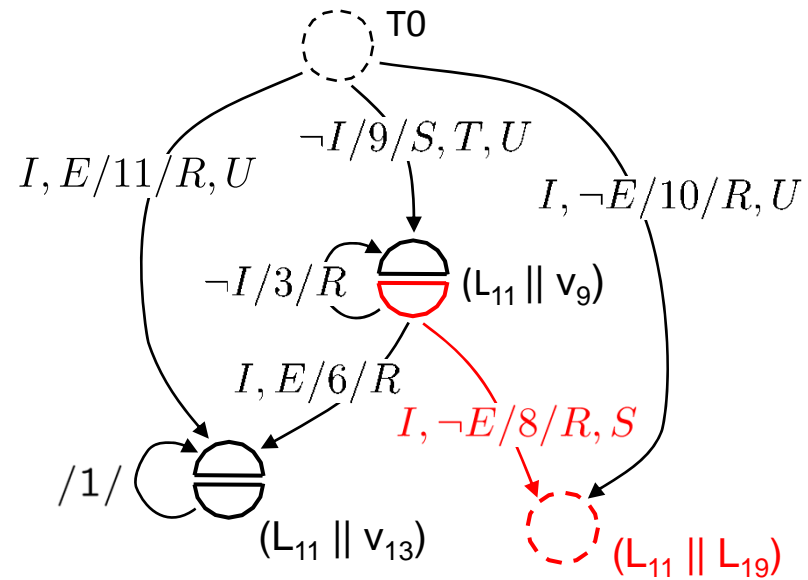
← tick

I present, E absent

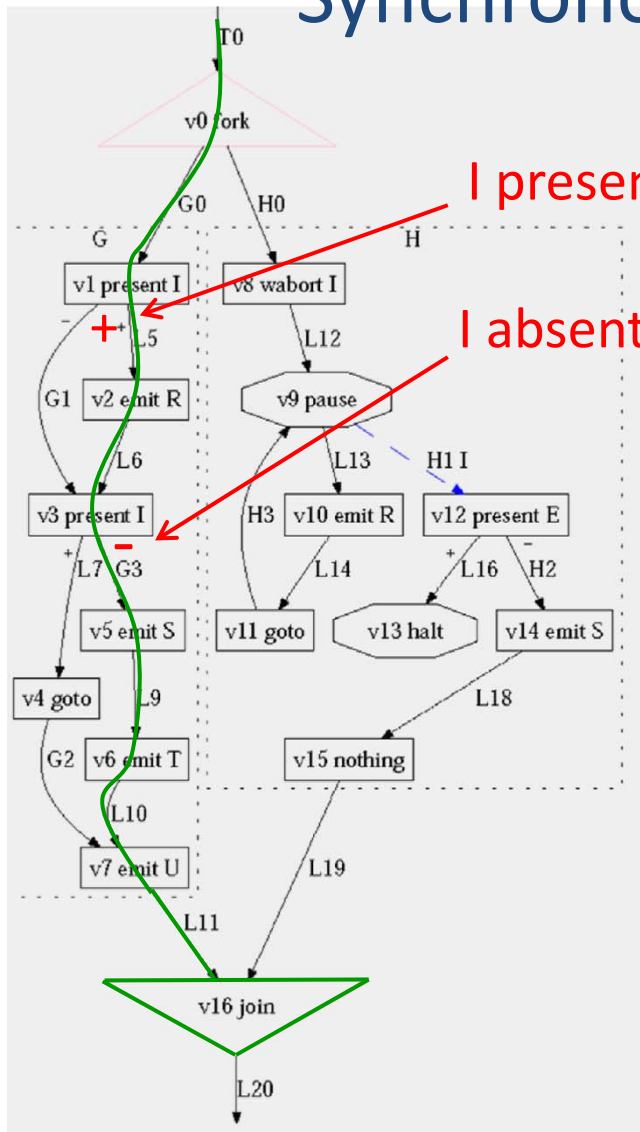
8 instruction cycles

→ instantaneous exit

R, S emitted



# Synchronous Multi-Threading



## (1) Intra-thread Exclusion

Path sensitization problem:  
sequential flow **not sensitizable**

=> Precise WCRT is  
**data-dependent**



NP hard !

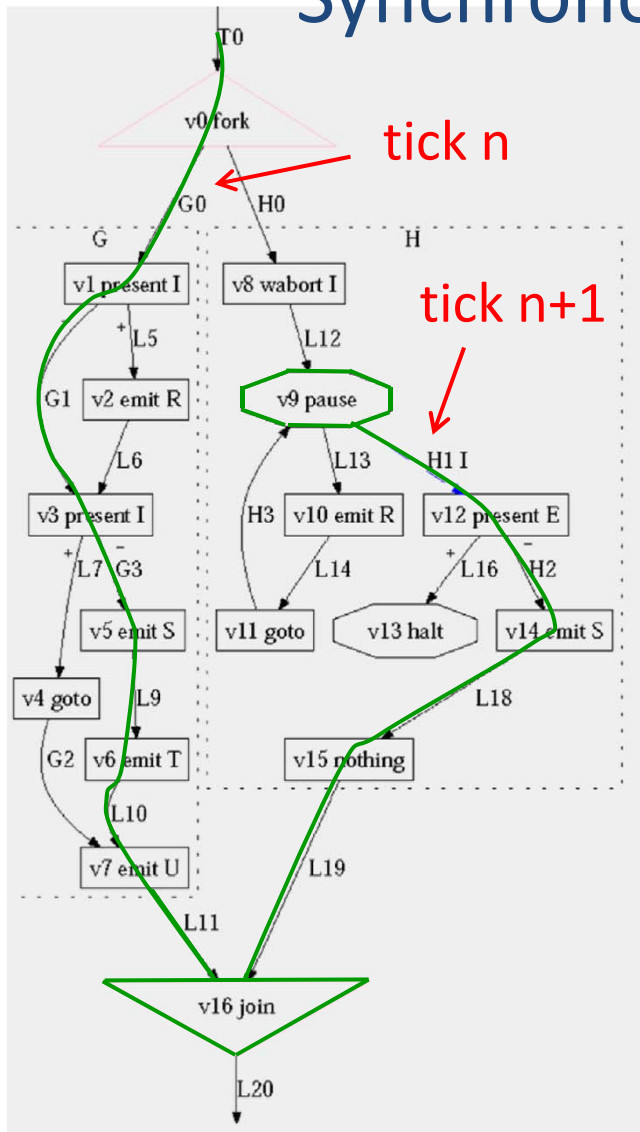
## Solution: Data Abstraction

=> Over-approximation

=> Longest Path Problem

=> PTime

# Synchronous Multi-Threading



(2) Inter-thread Exclusion  
Tick Alignment Problem (TAP):  
concurrent flow **not alignable**

## Data Abstraction

What if tick states of threads  
do not depend on data ?

Complexity of (Pure) TAP ?

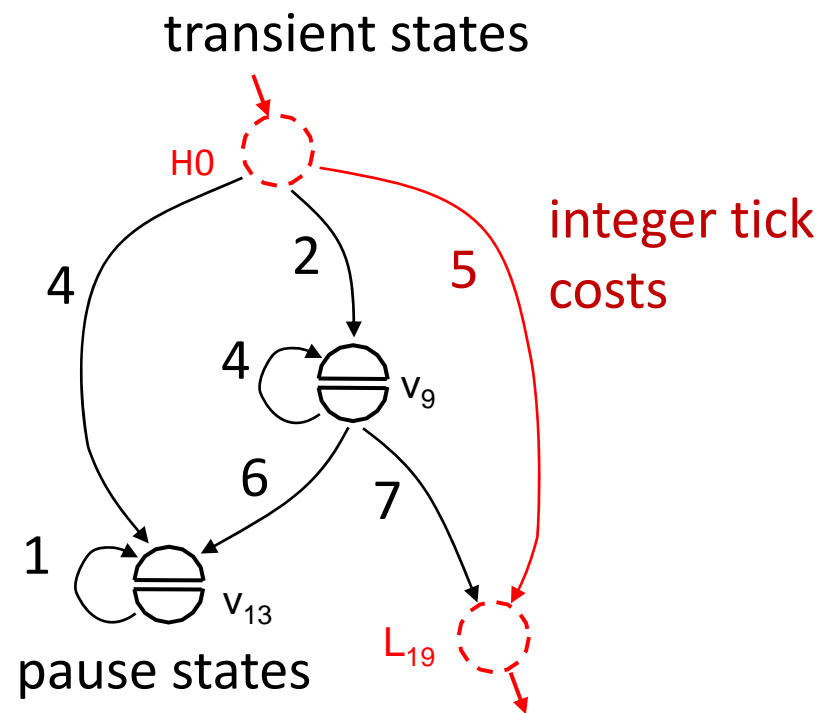
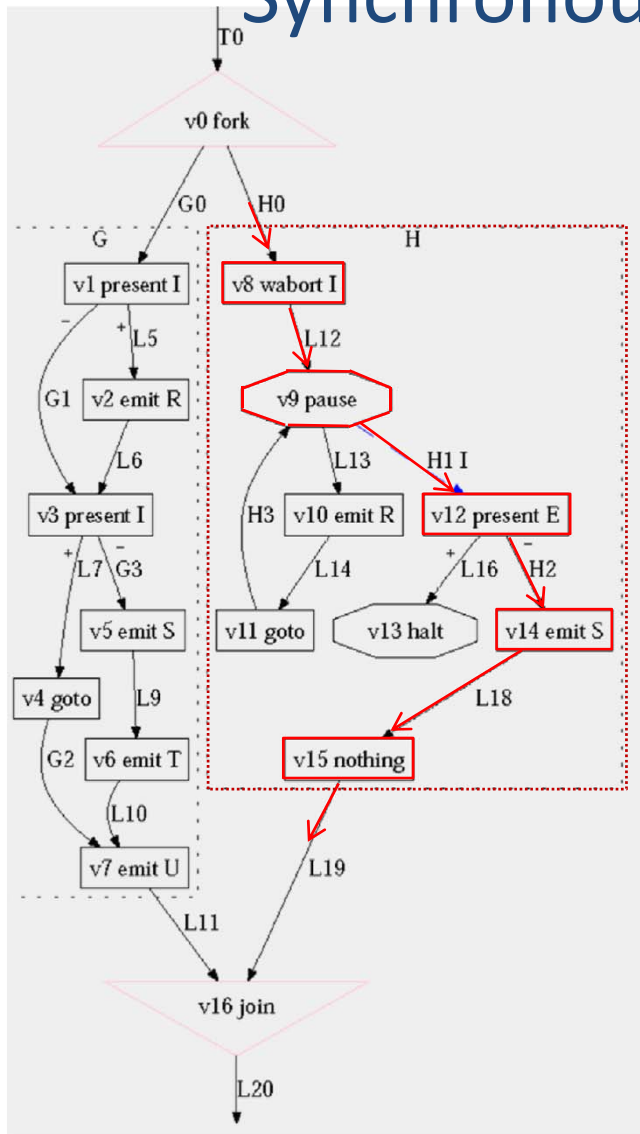




# 3

## TICK COST AUTOMATA (TCA) & TICK ALIGNMENT PROBLEM (TAP)

# Synchronous Tick Cost Automata





# Max-Plus Formal Power Series

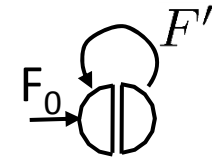
Max-Plus Algebra  $\mathbb{N}_\infty = (\mathbb{N} \cup -\infty, \oplus, \odot, -\infty)$  plus

Formal Power Series  $\mathbb{N}_\infty^*[X]$  max

$$F = F_0 \oplus F_1 X \oplus F_2 X^2 \oplus F_3 X^3 \dots = F_0 \oplus XF'$$

$$F' = F_1 \oplus F_2 X \oplus F_3 X^2 \oplus F_4 X^3 \dots$$

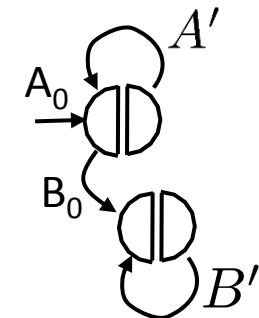
Scalars  $n = n \oplus -\infty X \oplus -\infty X^2 \oplus \dots$



## Sequential Composition (Expansion Law)

$$(A_0 \oplus XA') ; (B_0 \oplus XB') = (A_0 \odot B_0) \oplus X(A' \odot B_0 \oplus B')$$

$$A_0 ; (B_0 \oplus XB') = (A_0 \odot B_0) \oplus XB'$$



## Synchronous Product (Expansion Law)

$$(A_0 \oplus XA') \parallel (B_0 \oplus XB') = (A_0 \odot B_0) \oplus X(A' \parallel B')$$

# TCA = Recurrence Equations in $\mathbb{N}_\infty[X]$

## Recurrence

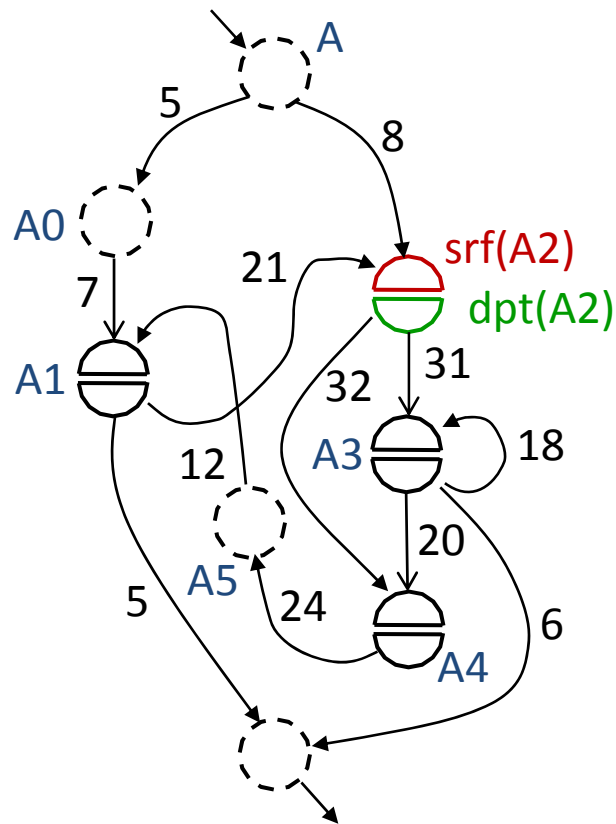
$$A = 5 ; A0 \oplus 8 ; \text{srf}(A2)$$

$$A0 = 7 ; \text{srf}(A1)$$

$$\text{srf}(A1) = 0 \oplus X \text{dpt}(A1)$$

$$\text{srf}(A2) = 0 \oplus X \text{dpt}(A2)$$

$$\text{dpt}(A1) = \dots$$



## Max-Plus Expansion

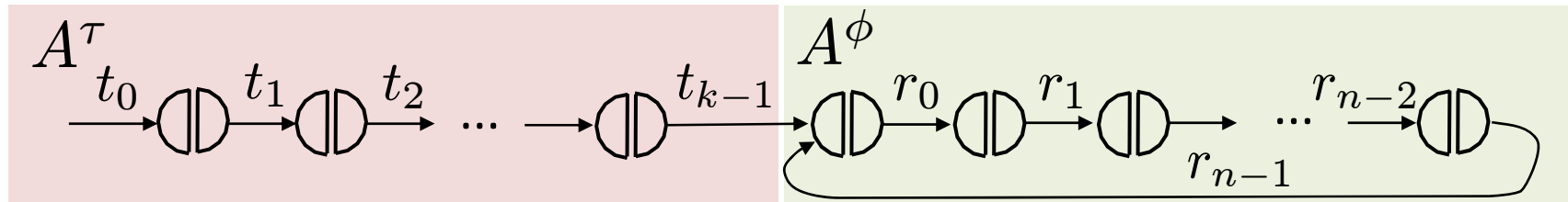
$$A[X] = 12 \oplus 32X \oplus 36X^2 \oplus 36X^3 \oplus \dots$$

## Worst Case Reaction Time

$$\text{wcr}(A) = A[0] = 36$$

# Linear TCAs (I-TCA)

$$A = A^\tau \oplus X^k A^\phi$$



$\tau(A) =_{df} k$  transient length

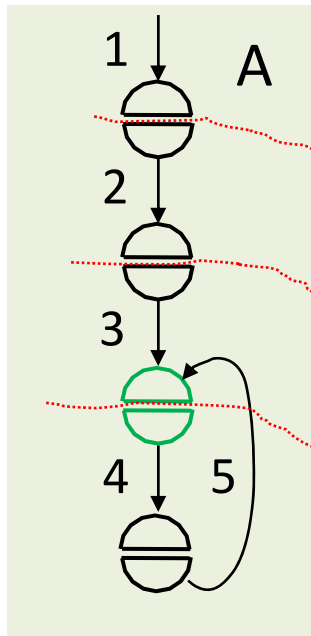
$\phi(A) =_{df} n$  cycle length

$A$  is a **monocyclic TCA** (m-TCA) if  $\tau(A) = 0$

**Proposition 1** *Every single-threaded TCA can be reduced to an equivalent I-TCA in polynomial time.*

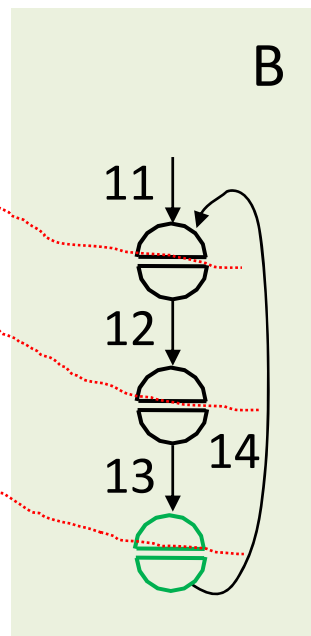
# Synchronous Product (Multi-threaded)

$$A = \bigoplus_i A(i)X^i \quad B = \bigoplus_i B(i)X^i \quad (A \parallel B) =_{df} \bigoplus_i (A(i) \odot B(i))X^i$$



$$\tau(A) = 3$$

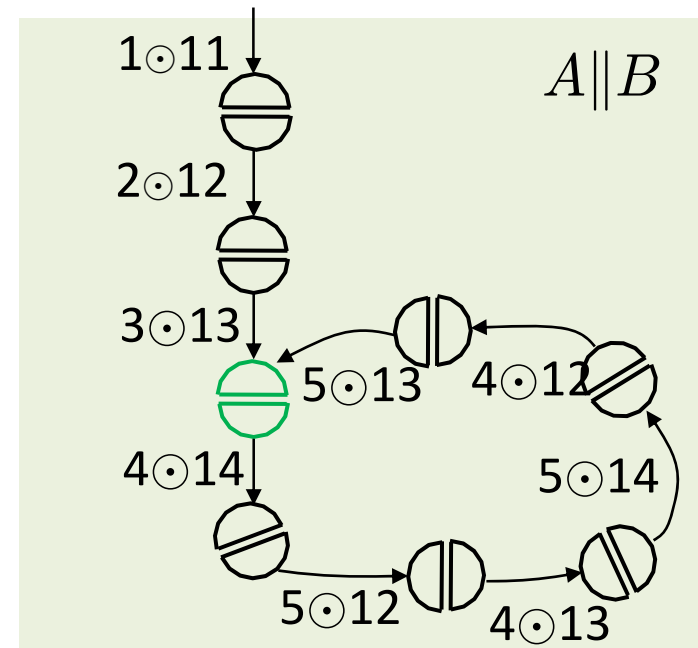
$$\phi(A) = 2$$



$$\tau(B) = 1$$

$$\phi(B) = 3$$

Product  
Expansion  
➔



$$\tau(A \parallel B) = 3 = \max(\tau(A), \tau(B))$$

$$\phi(A \parallel B) = 6 = \phi(A)\phi(B)$$

# TAP by State Exploration

**Definition 1** The *Tick Alignment Optimisation Problem TAP* is the problem to compute  $wcrt(T)$  for an arbitrary parallel composition  $T = T_1 \parallel T_2 \parallel \dots \parallel T_n$  of (single-threaded) TCAs  $T_i$ .

**Proposition 2** The TAP for  $l$ -TCAs can be reduced to TAP for  $m$ -TCAs in polynomial time.

## Algorithm 1 (Reachability, State Expansion)

Given TAP  $T = T_1 \parallel T_2 \parallel \dots \parallel T_n$  with  $m$ -TCAs:

1. Repeatedly use the Expansion Law to obtain the reduced linear form  $T^*$  of  $T$ .
2. Compute  $wcrt(T^*)$ .

⇒ Time complexity  $\Theta(n \text{ lcm}(\phi_1, \dots, \phi_n))$ .

**EXPONENTIAL**





# 4

# ALGORITHMS FOR TAP

# m-TAP Number Theory

## Proposition 3 (Chinese Remainder Theorem)

Given TAP  $T = T_1 \parallel T_2 \parallel \dots \parallel T_n$  with  $m$ -TCAs  $T_i$ . A *candidate sum* of the  $m$ TAP  $T$ ,

$$T_1(S_1) + T_2(S_2) + \dots + T_n(S_n),$$

for transition offsets  $0 \leq S_i < \phi_i$ , is *aligned* in  $T$  iff

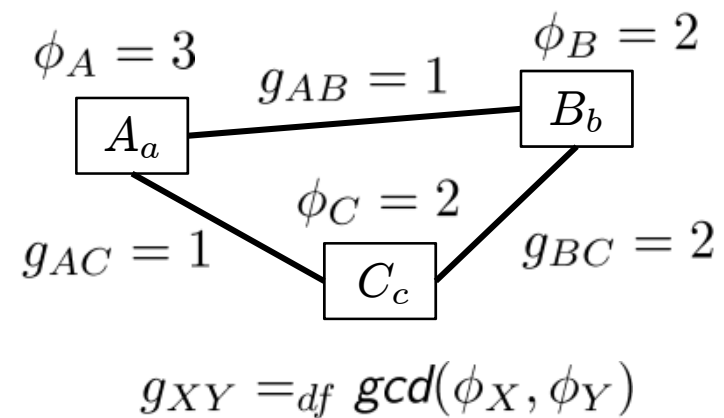
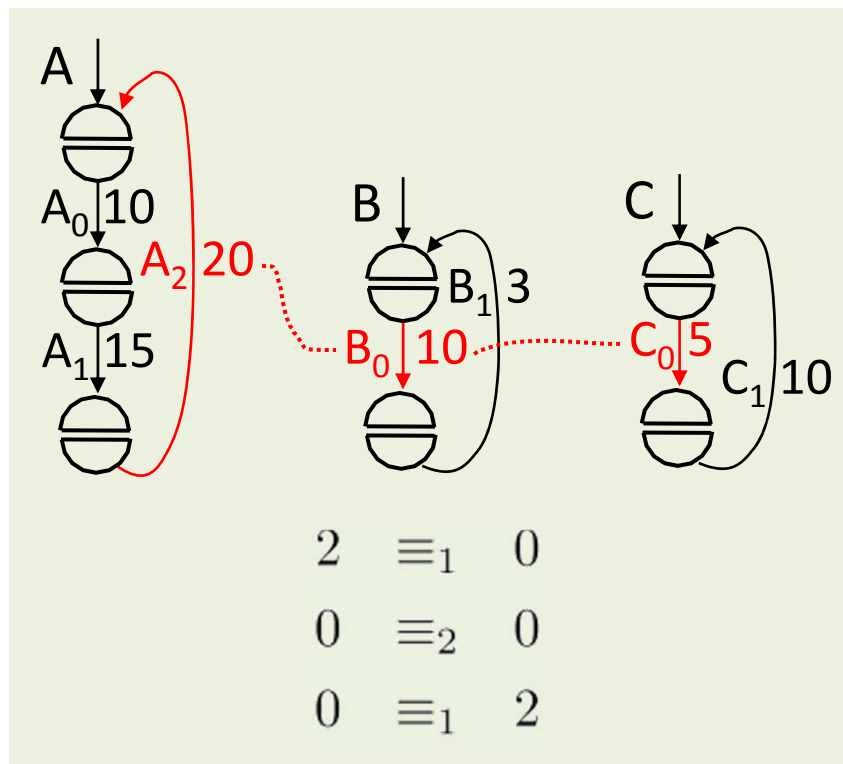
$$\forall 1 \leq i < j < n. S_i \equiv_{g_{ij}} S_j$$

where  $g_{ij} =_{df} \gcd(\phi_i, \phi_j)$ .

# m-TAP Number Theory

$$\text{wcr}(A \parallel B \parallel C) = \max(\text{AlignedSums})$$

$$\text{AlignedSums} = \{A_{k \bmod \phi_A} + B_{k \bmod \phi_B} + C_{k \bmod \phi_C} \mid k \geq 0\}.$$



$$a \equiv_{g_{AB}} b$$

$$b \equiv_{g_{BC}} c$$

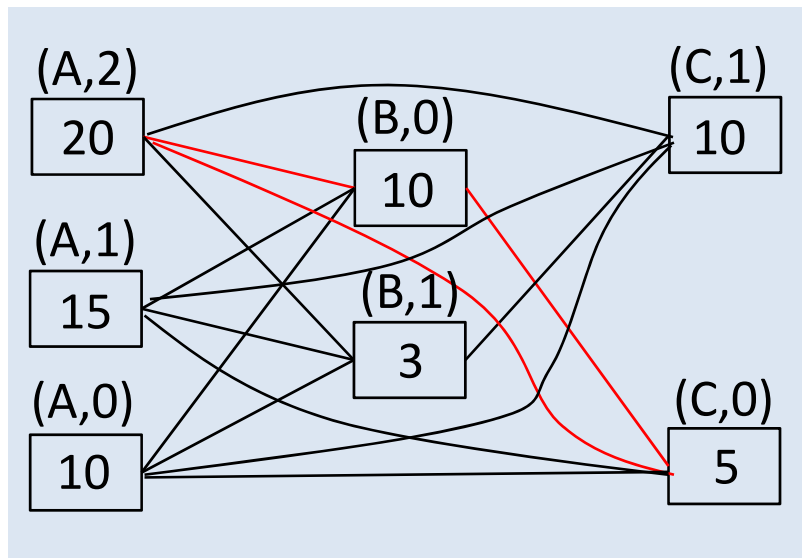
$$c \equiv_{g_{CA}} a$$



# Tick Alignment Graph TAG

TAP  $T = (T_1, T_2, \dots, T_n)$   $\phi_i =_{df} \phi(T_i)$   $g_{i_1 i_2} =_{df} \gcd(\phi_{i_1}, \phi_{i_2})$

The weighted undirected Tick Alignment Graph  $G_T$



TAG  $G_T = (V_T, E_T, w_T)$

$V_T =_{df} \{(i, j) \mid 1 \leq i \leq n, 0 \leq j \leq \phi_i\}$

$E_T =_{df} \{(i_1, j_2) \leftrightarrow (i_2, j_2) \mid j_1 \equiv_{g_{i_1 i_2}} j_2\}$

$w_T(i, j) =_{df} T_i(j)$

**Proposition 4** Given a TAP  $T$  of size  $O(nm)$  the associated TAG  $G_T$  can be computed in  $O(n^2m^2)$  time.

# Reduction of mTAP to Clique Problem

## Proposition 5

- A candidate sum  $S$  of the mTAP  $T$ ,

$$T_1(S_1) + T_2(S_2) + \cdots + T_n(S_n),$$

for  $0 \leq S_i \leq \phi_i$ , is aligned in  $T$  iff the nodes

$$S = \{(i, S_i) \mid 1 \leq i \leq n\}$$

form a *clique* in the TAG  $G_T$ .

- To check a candidate sum  $S$  is a clique takes  $O(n^2)$  time.
- $w_{\text{crt}}(T) = \max\{w(S) \mid S \text{ clique in } G_T\}$   
(Maximum Weight Clique Problem MWCP)

# Exact MWCP Algorithms

MWCP is known to be NP-complete



**Algorithm 2 (ILP)** [Pardalos & Xue 1992]

$$\max \sum_{(i,j) \in V_T} w_T(i,j) \cdot x_{i,j}$$

subject to  $x_{i_1, j_1} + x_{i_2, j_2} \leq 1$ , for all  $(i_1, j_1) \not\rightarrow_{E_T} (i_2, j_2)$

$$x_{i,j} \in \{0, 1\}, \text{ for all } (i, j) \in V_T$$

- depends on cleverness of general purpose ILP
- original problem structure lost
- difficult to twist & control search strategy

# Maximum Weighted Clique Algorithms

**Algorithm 3 (Branch and Bound)** [K. Yamaguchi & S. Masuda 2008]

$C_{max} = MWC(G_T, -1)$  where

$MWC((V, E), \theta)$

- 1 compute **ordering**  $V = \{\pi_0, \pi_1, \dots, \pi_{|V|-1}\}$  and **upper bound** weights  $UB(\pi_i) \geq w(D)$  any clique  $D$  with  $\pi_i \in D \subseteq \{\pi_0, \pi_1, \dots, \pi_i\}$ ;
- 2  $C := \emptyset$ ;
- 3 for  $i := |V| - 1$  downto 0 do
  - 3.1 if  $UB(\pi_i) \leq \theta$  then return  $C$
  - 3.2  $C' := MWC((V, E)@_{\pi_i}, \theta - w(\pi_i))$
  - 3.3 if  $C' \neq \emptyset$  then  $C := C' \cup \{\pi_i\}$  and  $\theta := w(C' \cup \{\pi_i\})$

## Reduction of MWCP to mTAP ?

**Proposition 6** *Let  $G$  be an undirected graph of size  $n$ . Subject to the time and space complexity of constructing  $O(n^2)$  distinct prime numbers  $p_i$ , the MWCP for  $G$  can be reduced to the mTAP for  $T_G$  of size  $O(n \prod_i p_i)$ .*

= **Exponential time/space reduction** to “explicit” TAP

- **Not much use** for lower bound on complexity of mTAP
- If there is no polynomial reduction from MWCP, maybe mTAP is polynomial ?



# WHO CARES ABOUT EXACT WCRT ?

## Approximate MWCP

Good upper bounds may be enough !

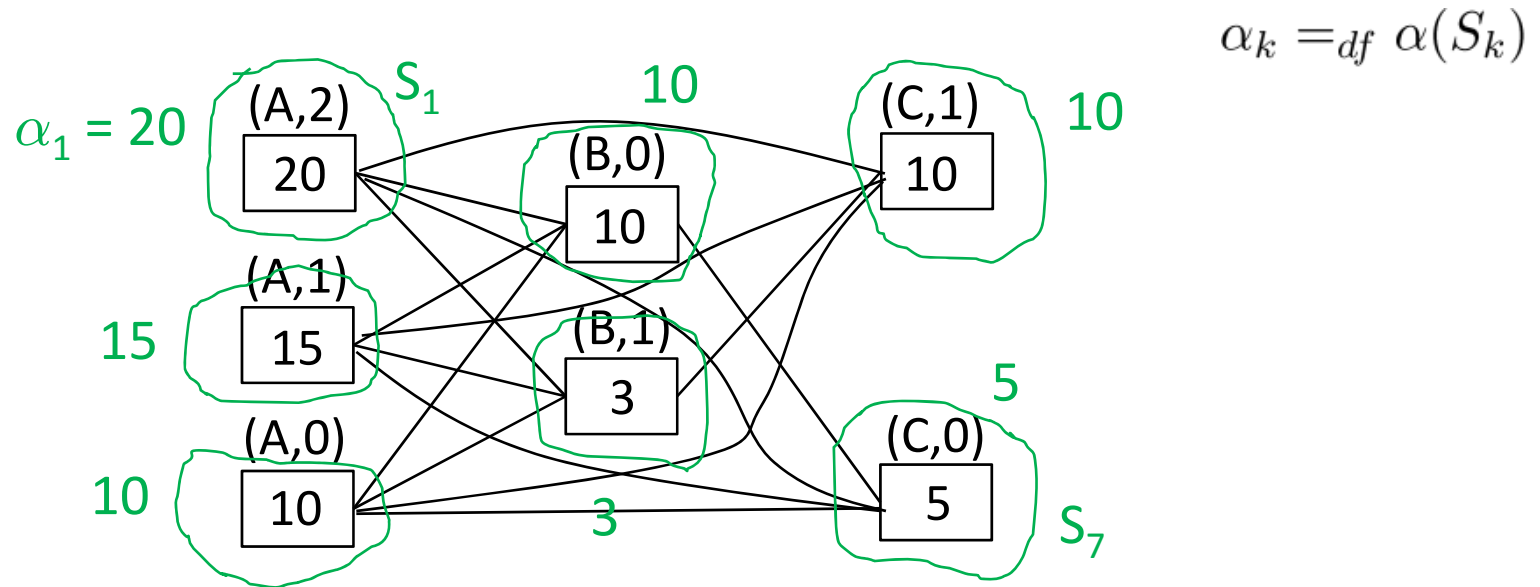
- There are two basic techniques
  - „Plus-Max“ Approach  
e.g., Weighted Vertex Coloring ...
  - „Max-Plus“ Approach  
e.g., Constraint Relaxation ...



# PLUS-MAX: VERTEX COLORING



# Weighted Coloring Example



Singleton coloring generates trivial upper bound for WCRT:

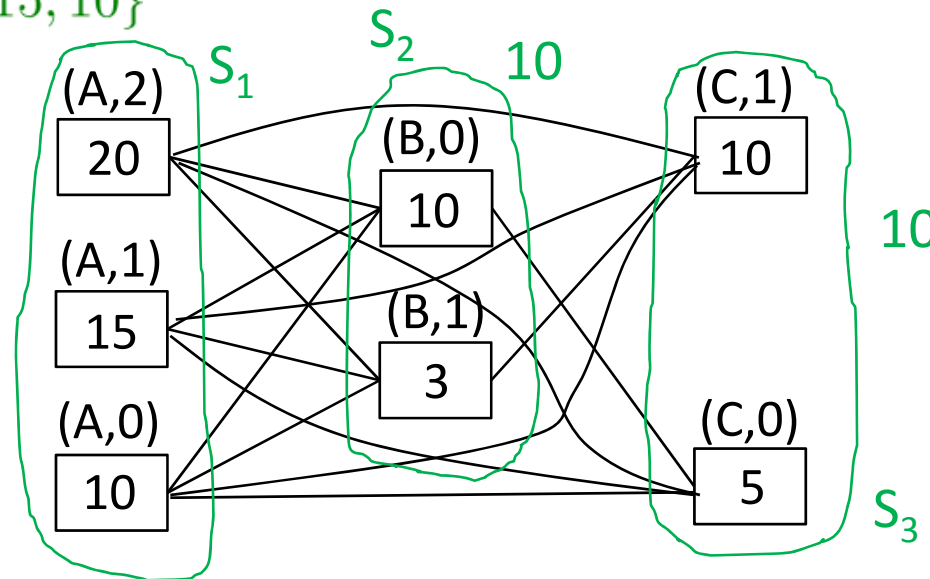
$$\begin{aligned}
 w(S) &= \sum_{(i,j) \in V_T} w_T(i,j) \\
 &= 20 + 15 + 10 + 10 + 3 + 10 + 5 = 73
 \end{aligned}$$

# Weighted Coloring Example

$$\alpha_1 = \max\{20, 15, 10\}$$

$$= 20$$

$$\alpha_k =_{df} \alpha(S_k)$$



Thread coloring generates „Plus-Max“ upper bound for WCRT:

$$w(S) = \sum_i \max_j \{w_T(i, j)\}$$

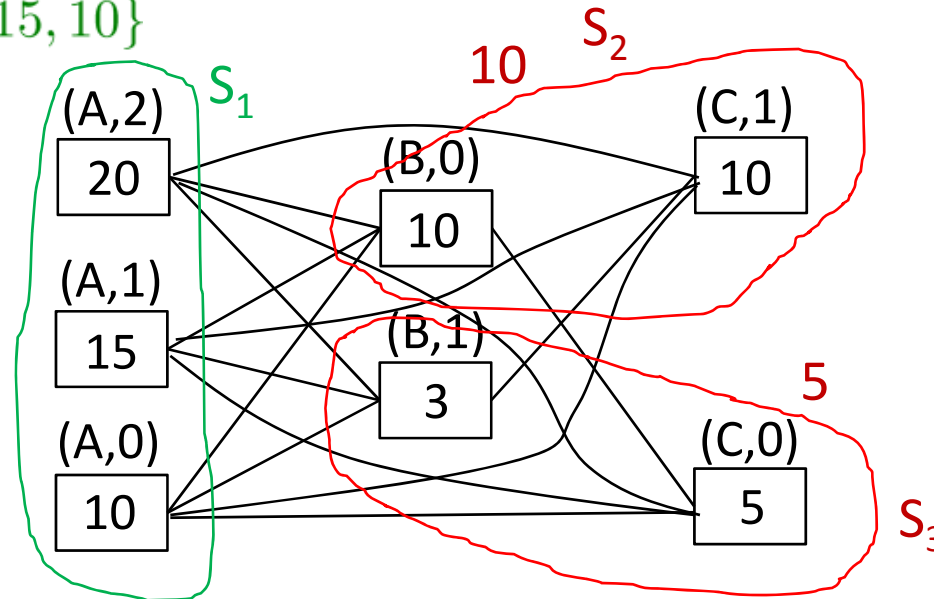
$$= \max\{20, 15, 10\} + \max\{10, 3\} + \max\{10, 5\} = 40$$

# Weighted Coloring Example

$$\alpha_1 = \max\{20, 15, 10\}$$

$$= 20$$

$$\alpha_k =_{df} \alpha(S_k)$$



General coloring generates **minimal upper bound** for WCRT:

$$w(S) = \max\{20, 15, 10\} + \max\{10, 10\} + \max\{3, 5\} = 35$$

**Beware: Minimal Weighted Covering is NP-complete** 



# **MAX-PLUS: CONSTRAINT RELAXATION**

# Relaxation for Max-Plus Upper Bounds

Relax the connectivity constraint: **Maximum weight „pre-cliques“**

$C$  clique  $\Rightarrow$   $C$  pre-clique

$$\text{wcr}(T) \leq \max \left\{ \sum_{(i,j) \in X} w_T(i,j) \mid X \subseteq V_T \text{ pre-clique} \right\}$$

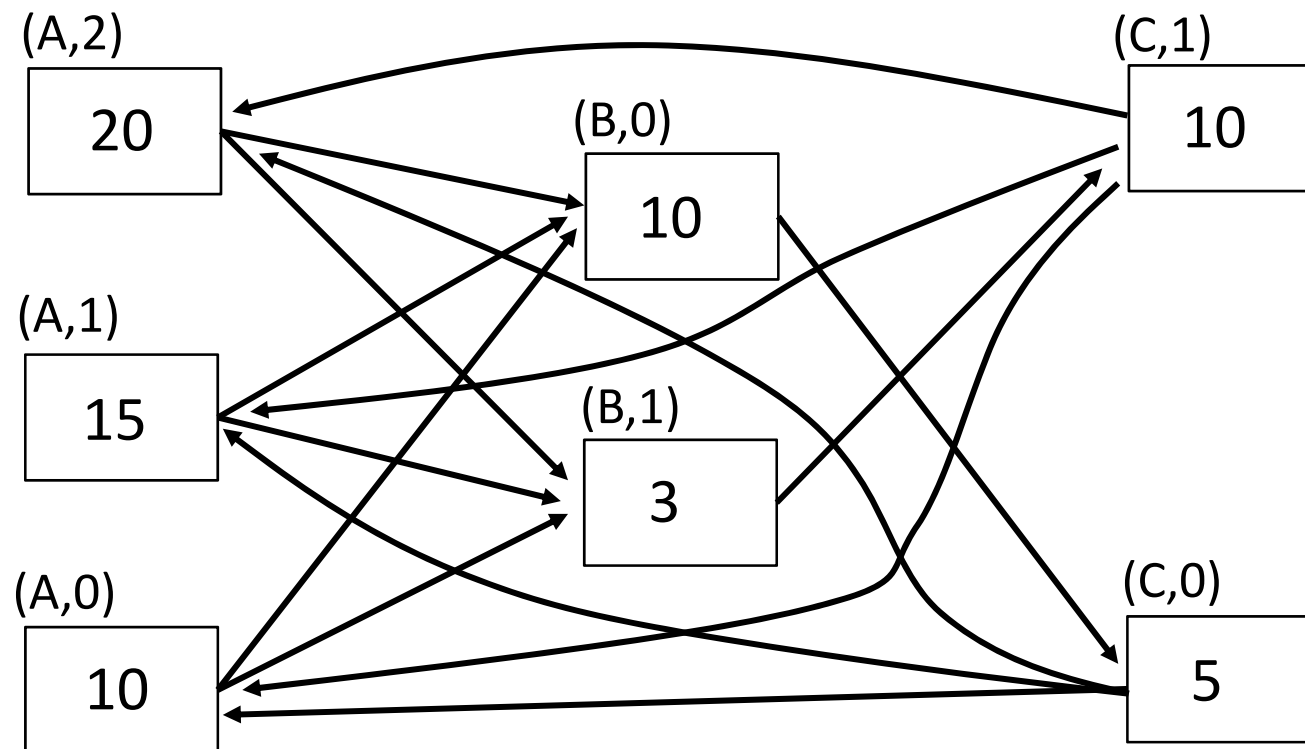
## Notions of Pre-cliques

- **subset**:  $X = V_T$ , sum of all weights  $\sum_{(i,j) \in V_T} w_T(i,j)$
- **subset containing at most one node from each thread**:  
same as Plus-Max  $\sum_i \max_j \{w_T(i,j)\}$
- **triangulated subgraph**
- **cycle containing at most one node from each thread**  
(Maximum Cycle Mean Problem)

• **Good News**: These can be computed in **polynomial time**

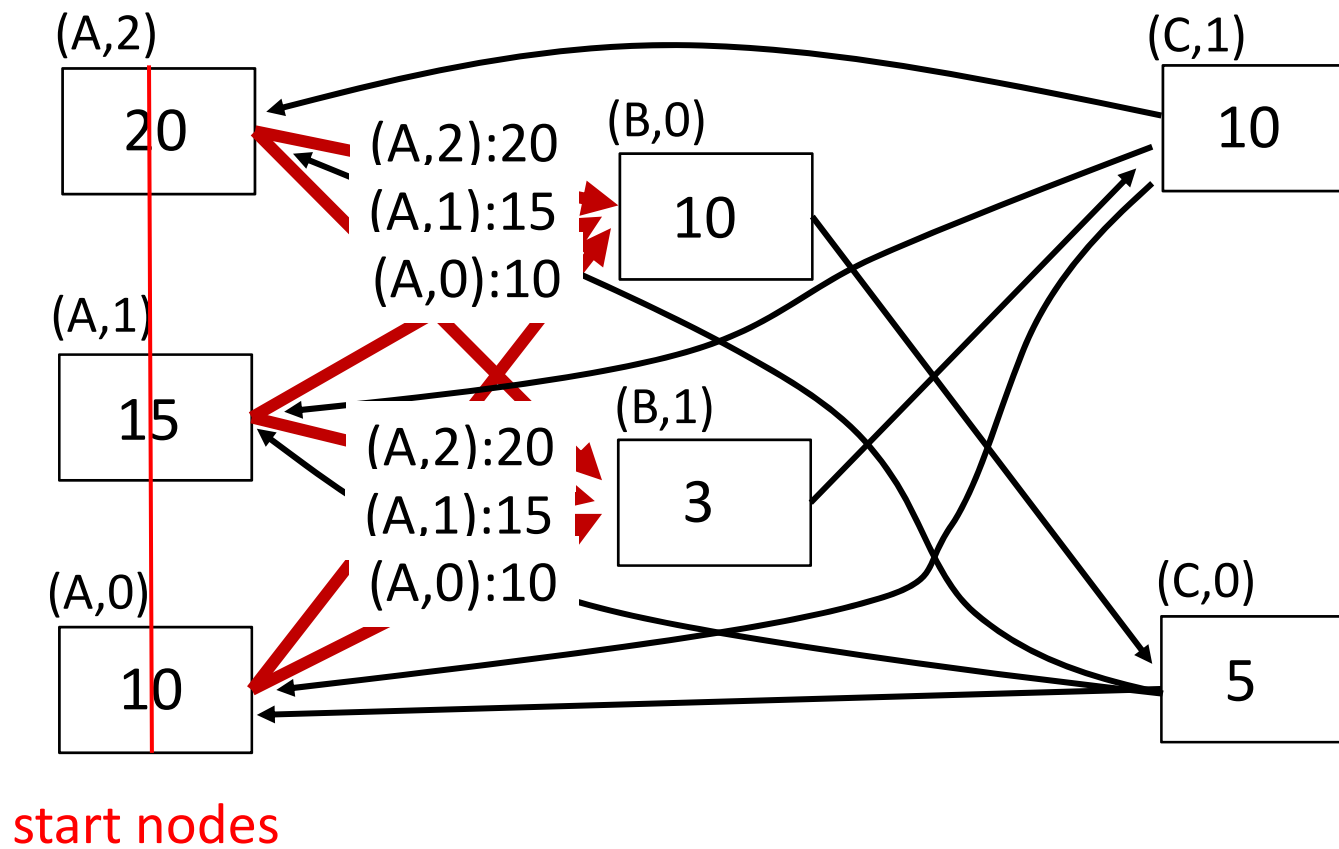
# Maximum Cycle Relaxation Example

Ordered Threads, Directed edges A  $\rightarrow$  B  $\rightarrow$  C  $\rightarrow$  A



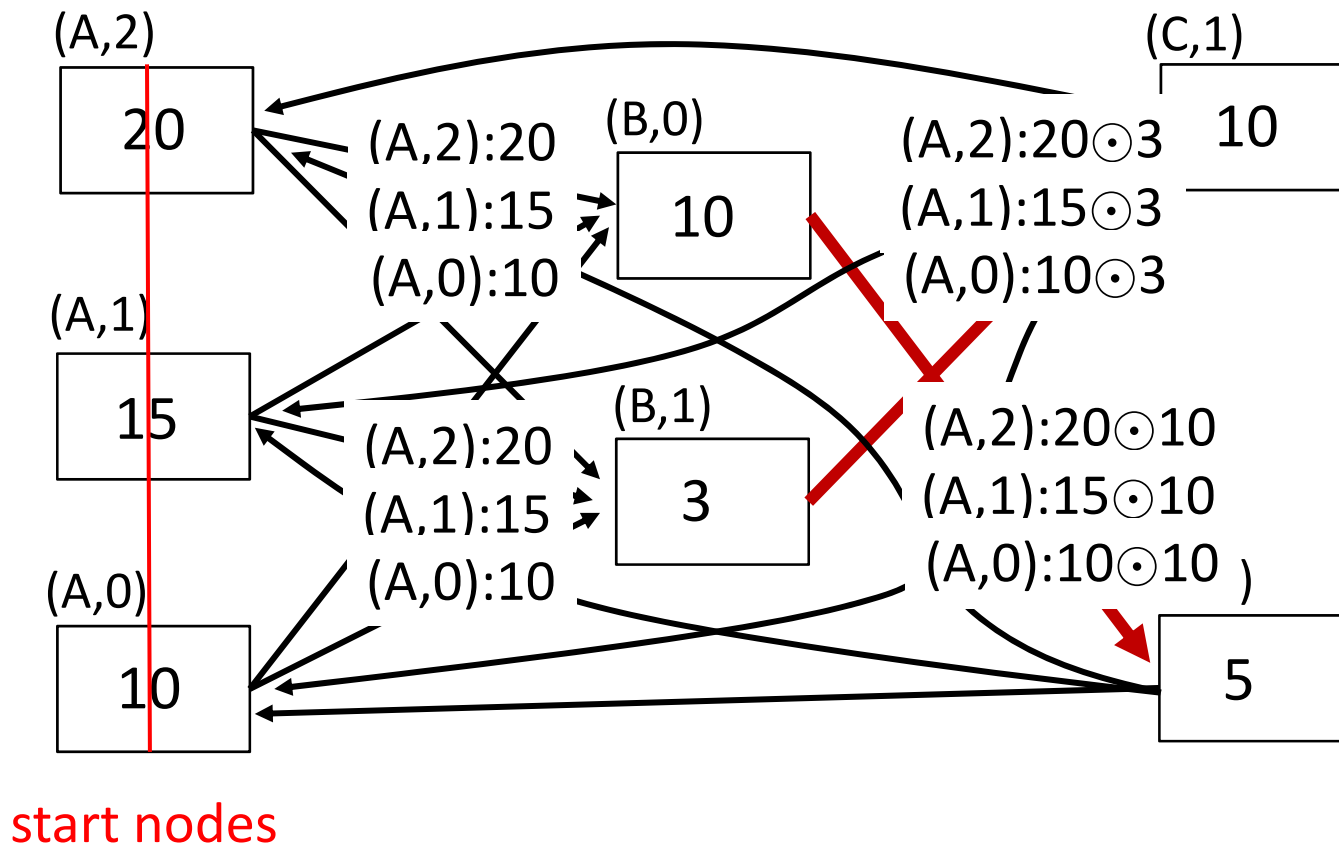
# Maximum Cycle Relaxation Example

Ordered Threads, Directed edges A -> B -> C -> A



# Maximum Cycle Relaxation Example

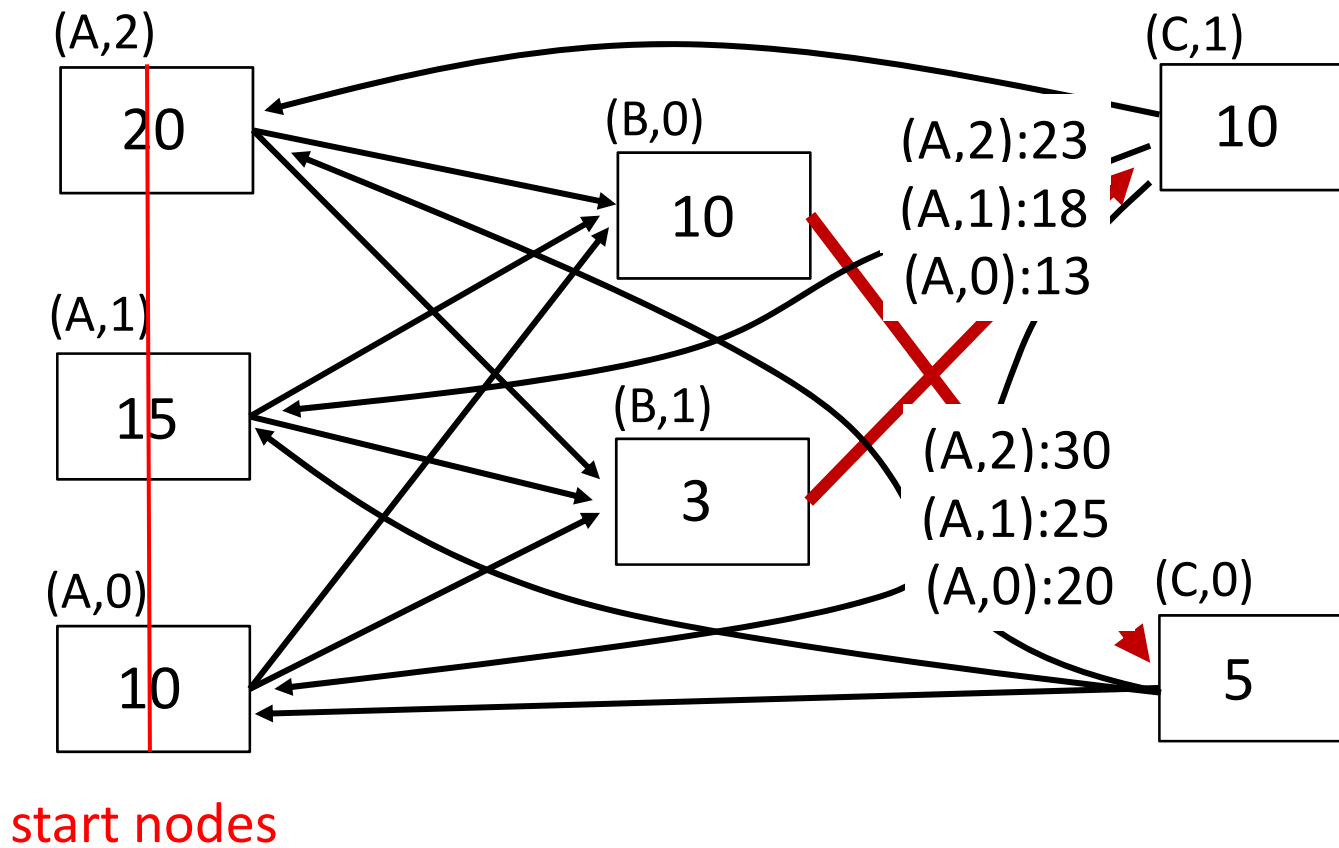
Ordered Threads, Directed edges A -> B -> C -> A





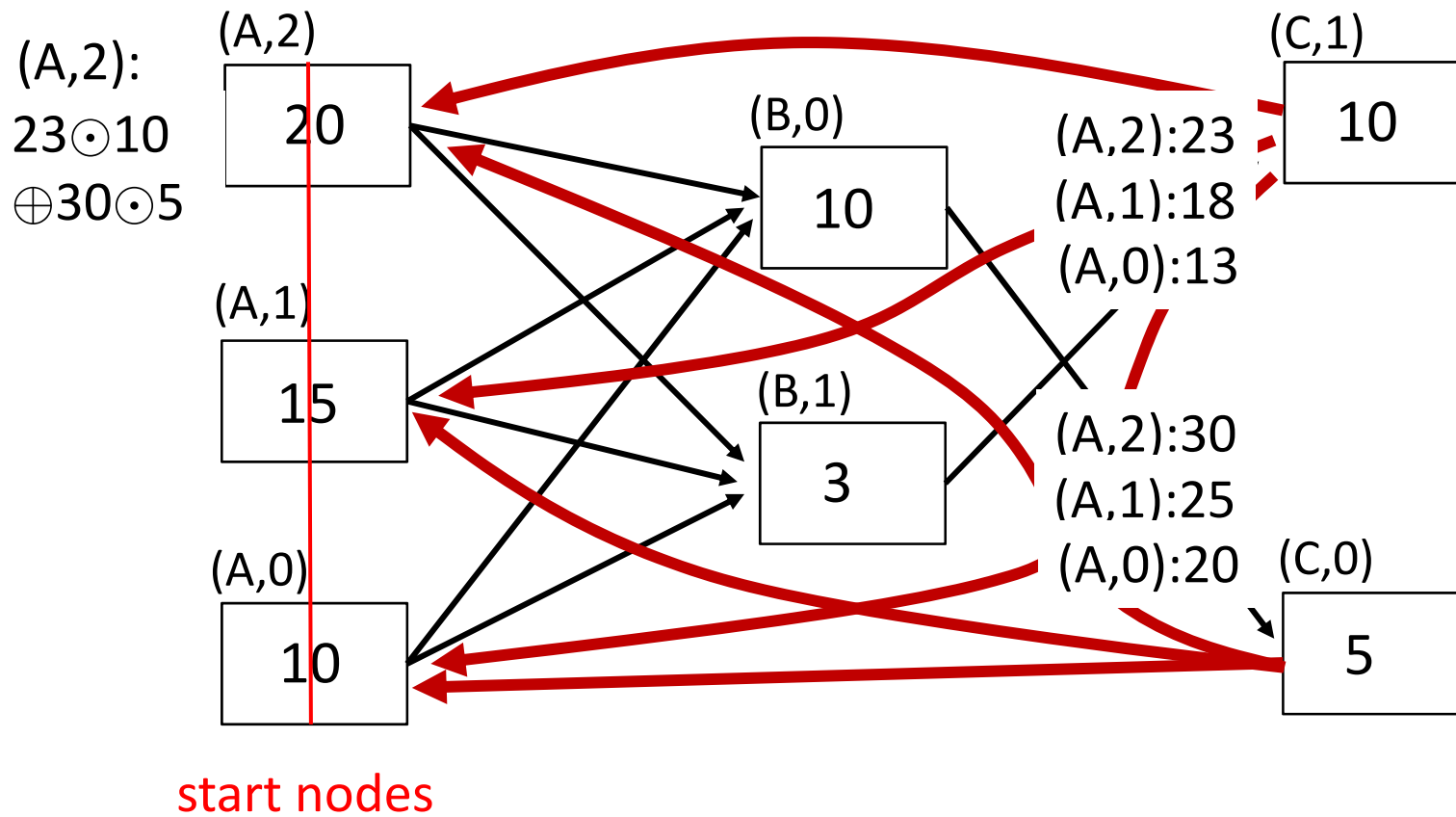
# Maximum Cycle Relaxation Example

Ordered Threads, Directed edges A -> B -> C -> A



# Maximum Cycle Relaxation Example

Ordered Threads, Directed edges A -> B -> C -> A





# 5 CONCLUSION

## What's the Message ?

- Tick Alignment (even without data-dependency) is a non-trivial computational problem
- Conjecture
  - **Unknown** if TAP is NP-hard
  - **Polynomial Approximations** can be found which give the **exact WCRT „most of the time“**  
(remember Pascal Raymond's talk)
- Experiments still outstanding ...