Is Timing Analysis a Refinement of Causality Analysis?

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Why Causality Analysis is Important

Causality analysis needs to be taken seriously.

"For acyclic circuits the analysis is unnecessary, only a problem for Esterel not for other languages such as Lustre"

The key difference between cyber physical and embedded systems is that the former are subject to strong physical control. The term "cyber" comes from "Kybernetik" and means control loops.

But control loops are (instantaneous) cyclic interactions, and causality analysis (stability, convergence) is an essential ingredient in control theory!

Playing The Maze Game



Program of the Maze

```
emit a
present d then emit b end
present a then
    present d else emit f end
end
present a else
    present b then emit c end
end
present e then emit h end
present b else
    present g then emit e end
end
present e then emit q end
```

Sequential Block



Sequential Block + Timing Information G0 δ_1 v_1 : present Ι Т L5 δ_2 emit R G1 v_2 : δ_1 L6 + v_3 : present Ι G3 δ_2 L7 v_5 : emit S δ_3 goto v_4 : L9 δ_2 v_6 : emit Τ G2 δ_2 L10 emit v_7 : U L11

Two-Player Timed Maze





$[\delta_1]: G0 \wedge I \supset \circ L5$



$[\delta_1]: G0 \wedge I \supset \circ L5$

 $[\delta_1]: G0 \land \neg I \supset \circ G1$



$$\begin{split} &[\delta_1]: G0 \land I \supset \circ L5 \\ &[\delta_2]: L5 \supset \circ L6 \end{split}$$

 $[\delta_1]: G0 \land \neg I \supset \circ G1$



$$\begin{split} & [\delta_1]: G0 \land I \supset \circ L5 & [\delta_1]: G0 \land \neg I \supset \circ G1 \\ & [\delta_2]: L5 \supset \circ L6 & [\delta_1 \delta_1]: (L6 \lor G1) \land I \supset \circ L7 \end{split}$$

$$\begin{array}{ll} v_1^+ = [\delta_1] : G0 \land I \supset \circ L5 & v_2 = [\delta_2] : L5 \supset \circ L6 \\ v_1^- = [\delta_1] : G0 \land \neg I \supset \circ G1 & v_5 = [\delta_2] : G3 \supset \circ L9 \\ v_3^+ = [\delta_1 \delta_1] : (L6 \lor G1) \land I \supset \circ L7 & v_4 = [\delta_3] : L7 \supset \circ G2 \\ v_3^- = [\delta_1 \delta_1] : (L6 \lor G1) \land \neg I \supset \circ G3 & v_6 = [\delta_2] : L9 \supset \circ L10 \\ v_7 = [\delta_2 \delta_2] : (G2 \lor L10) \supset \circ L11 \end{array}$$

This specification is **open**: It does not preclude that the context adds extra jumps into or emissions in G.

$$\begin{array}{ll} v_1^+ = [\delta_1] : G0 \land I \supset \circ L5 & v_2 = [\delta_2] : L5 \supset \circ L6 \\ v_1^- = [\delta_1] : G0 \land \neg I \supset \circ G1 & v_5 = [\delta_2] : G3 \supset \circ L9 \\ v_3^+ = [\delta_1 \delta_1] : (L6 \lor G1) \land I \supset \circ L7 & v_4 = [\delta_3] : L7 \supset \circ G2 \\ v_3^- = [\delta_1 \delta_1] : (L6 \lor G1) \land \neg I \supset \circ G3 & v_6 = [\delta_2] : L9 \supset \circ L10 \\ v_7 = [\delta_2 \delta_2] : (G2 \lor L10) \supset \circ L11 \end{array}$$

This specification is **open**: It does not preclude that the context adds extra jumps into or emissions in G.

$$G0 \wedge I \supset \circ L5$$

Species that L5 is activated (with delay) whenever control reaches G0 but not what happens if G0 is never activated.

$$\begin{array}{ll} v_1^+ = [\delta_1] : G0 \land I \supset \circ L5 & v_2 = [\delta_2] : L5 \supset \circ L6 \\ v_1^- = [\delta_1] : G0 \land \neg I \supset \circ G1 & v_5 = [\delta_2] : G3 \supset \circ L9 \\ v_3^+ = [\delta_1 \delta_1] : (L6 \lor G1) \land I \supset \circ L7 & v_4 = [\delta_3] : L7 \supset \circ G2 \\ v_3^- = [\delta_1 \delta_1] : (L6 \lor G1) \land \neg I \supset \circ G3 & v_6 = [\delta_2] : L9 \supset \circ L10 \\ v_7 = [\delta_2 \delta_2] : (G2 \lor L10) \supset \circ L11 \end{array}$$

In an **open** system L5 may still be activated by jumps from the program environment of G

 $G0 \wedge I \supset \circ L5$



$$\begin{array}{ll} v_1^+ = [\delta_1] : G0 \land I \supset \circ L5 & v_2 = [\delta_2] : L5 \supset \circ L6 \\ v_1^- = [\delta_1] : G0 \land \neg I \supset \circ G1 & v_5 = [\delta_2] : G3 \supset \circ L9 \\ v_3^+ = [\delta_1 \delta_1] : (L6 \lor G1) \land I \supset \circ L7 & v_4 = [\delta_3] : L7 \supset \circ G2 \\ v_3^- = [\delta_1 \delta_1] : (L6 \lor G1) \land \neg I \supset \circ G3 & v_6 = [\delta_2] : L9 \supset \circ L10 \\ v_7 = [\delta_2 \delta_2] : (G2 \lor L10) \supset \circ L11 \end{array}$$

If we want to make L5 inaccessible from outside, we close the specification with an extra clause.

$$G0 \land I \supset \circ L5$$
$$\neg G0 \bigoplus \neg I \supset \circ \neg L5$$

$$(L_5) \rightarrow (\delta_1) \rightarrow G_0$$

$$I$$

$$\begin{array}{ll} v_1^+ = [\delta_1] : G0 \land I \supset \circ L5 & v_2 = [\delta_2] : L5 \supset \circ L6 \\ v_1^- = [\delta_1] : G0 \land \neg I \supset \circ G1 & v_5 = [\delta_2] : G3 \supset \circ L9 \\ v_3^+ = [\delta_1 \delta_1] : (L6 \lor G1) \land I \supset \circ L7 & v_4 = [\delta_3] : L7 \supset \circ G2 \\ v_3^- = [\delta_1 \delta_1] : (L6 \lor G1) \land \neg I \supset \circ G3 & v_6 = [\delta_2] : L9 \supset \circ L10 \\ v_7 = [\delta_2 \delta_2] : (G2 \lor L10) \supset \circ L11 \end{array}$$

The WCRT for G amounts to obtaining the worst-case (tightest) bound δ such that:

$$\bigwedge_{i=1}^{7} v_i^{\{+,-\}} \leq [\delta]: G0 \land (I \bigoplus \neg I) \supset \circ L11$$

where $\varphi \leq \psi$ (models inclusion): All schedules that satisfy φ also satisfy ψ .

Abstraction: Over and Under approximation

This is a standard abstraction.



 $[\delta_1 \ \delta_1]: \ G0 \land (I \oplus \neg I) \supset \circ G1 \oplus \circ L5$

The associated type specifies that any set of schedules passing through G0 when signal I is decided splits non-deterministically into a subset satisfying $\circ G1$ and other satisfying $\circ L5$.

This is a standard abstraction.



 $[\delta_1 \ \delta_1]: \ G0 \supset \circ G1 \bigoplus \circ L5$

This is a standard abstraction.



 $[\delta_1 \ \delta_1]: \ G0 \supset \circ G1 \bigoplus \circ L5$

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 $[\delta_1 \ \delta_1]: \ G0 \supset \circ G1 \bigoplus \circ L5$
















1

3

5

Assume that for the WCRT we are not interested in the exact timing of the side inputs.

$$0$$

$$-\infty : G0 \supset \circ G0 \oplus \circ L10 \oplus \circ G1$$

$$-\infty$$

$$-\infty \quad 0 \quad 1$$

$$-\infty \quad 1 \quad \cdot -\infty = 3 \quad : G0 \supset \circ G1 \oplus \circ G3 \oplus \circ L11$$

$$1 \quad 3 \quad -\infty \quad 5$$





$$1 \\ 3 : G0 \supset \circ G1 \bigoplus \circ G3 \bigoplus \circ L11 \\ 5$$

Can we also suppress the references to side outputs on the right of the scheduling type?

$$G0 \land \neg G1 \land \neg G3 \supset \circ f \oplus \circ f \oplus \circ L11$$



Playing The Maze Game

$$P ::= 0 \quad \text{nothing}$$

$$| !s \quad \text{emit } s$$

$$| s^+?(P) \quad \text{present } s \text{ then } P \text{ end}$$

$$| s^-?(P) \quad \text{present } s \text{ else } P \text{ end}$$

$$| P | P \quad P || P$$

$$| P; P \quad P; P$$

$$| P \setminus s \quad \text{signal } s \text{ in } P \text{ end}$$

Esterel more general choice statement: present s then P_1 else P_2 end can be recovered by the construct: $s^+?(P_1) \mid s^-?(P_2).$

Mazes are finite graphs with two types of directed edges, namely *visible* and *secret*.

These graphs are represented as systems of unfolding rules

$$M \coloneqq (x \leftarrow m_x)_{x \in V}$$

in a language of mazes, for some finite set of variables V representing *rooms* and *maze terms* m_x .

We write $m\{m'/x\}$ for the syntactic substitution that replaces all free occurrences of x by term m' in m.

Maze terms are defined in a process algebraic fashion:

$$m \coloneqq 0 \mid x \mid \iota.m \mid \tau.m \mid \sum_{i \in I} m_i \mid \mu x.m$$

Intuitively, 0 is a *dungeon*, ι . m (τ . m) represents a room with a *visible* (*secret*) corridor to room m.

 $\sum_{i \in I} m_i$ corresponds to a room that *merges* all rooms m_i with $i \in I$ and we write $m_1 + m_2$ for $\sum_{i \in \{1,2\}} m_i$.

If $x \leftarrow m_x$ is the *unfolding rule* defining room x then x corresponds to the *term* m_x and $\mu x. m_x$ is the *least fixed-point* solution for x.

The game-theoretic semantics of maze M requires the introduction of a labelled transition system $\langle \mathcal{M}, \{\iota, \tau\}, \rightarrow \rangle$ where \mathcal{M} is the set of *rooms*, $\{\iota, \tau\}$ is the *alphabet* and \rightarrow is the *transition relation* representing corridors defined by:

$$\overline{\gamma.m \xrightarrow{\gamma} m}$$

$$\frac{m_{j} \xrightarrow{\gamma} m_{j}'}{\sum_{i \in I} m_{i} \xrightarrow{\gamma} m_{j}'} j \in I$$
$$\frac{m\{\mu x. m/x\} \xrightarrow{\gamma} m'}{\mu x. m \xrightarrow{\gamma} m'}$$

2.

 $\frac{m \xrightarrow{\gamma} m'}{x \xrightarrow{\gamma} m'} x \Leftarrow m$

where γ ranges over { ι, τ }.











A maze play is determined by the players' strategies.

A strategy is a (partial) function: $\alpha : \mathcal{M} \to {\iota, \tau} \times \mathcal{M}$ such that , for all $m \in \mathcal{M}$ if $\alpha(m) = (\alpha_1(m), \alpha_2(m))$ is defined then



A strategy does not depend on the opponent's strategy or on a play history.

Given strategies α and β for players P and O, the play $play(\alpha, \beta, m)$ is the maximal path in M starting in room m with player P.

A player has a *winning strategy*, if he is always able to drive his opponent into a dungeon no matter which strategy his opponent employs and always assuming that *P* starts the game.

If player *P* has a winning strategy for room *x*, then *x* is a *winning position*. If player *O* has a winning strategy, then *x* is a *losing position*.

If both players can always avoid dungeons, thus engaging in infinite plays, neither player wins and the play ends in a *draw*.

A position that is neither a wining or a losing position is referred to as a *draw position*.

Technically, strategies within a maze *M* correspond to the must- and cannot-analysis (Esterel) of the associated program, which forms the basis of Esterel causality analysis.









Representing Programs as Mazes

With each program *P*, we associate a maze:

 $M \coloneqq (a \leftarrow \langle \langle P \rangle \rangle_a \{0/\delta\})_{a \in S \cup \{\lambda\}}$

The elements in $S \cup \{\lambda, \delta\}$ play the role of term variables representing rooms.

There is no rule $\delta \leftarrow \langle \langle P \rangle \rangle_{\delta}$ for the connecting variable δ .

In general, $\langle \langle P \rangle \rangle_a$ with describes the game conforming to P that can be played starting in room a modulo some conditions (dependencies) yet to be defined where instances of δ appear.



Representing Programs as Mazes

 $\langle \langle x^+? \, y^-? \, ! \, a \rangle \rangle$



$$\langle \langle x^+?!a | y^+?!a \rangle \rangle$$



Representing Programs	as Ma	azes
$\langle \langle P_1 \rangle \rangle_{\lambda} $ $(t) $ $(a_2) $	$\langle \langle \langle P_2 \rangle \rangle$	a
	<i>a</i> ₁	t
	W	χ
$\langle a_1 \rangle \langle a_2 \rangle$	L	W
	L	D
$\langle \langle P_1 \rangle \rangle_a$	L	D
	L	D
(a)	D	D

 $\langle \langle P_1; P_2 \rangle \rangle_a := \tau . \langle \langle P_1 \rangle \rangle_a + \iota . (\iota . \langle \langle P_1 \rangle \rangle_\lambda + \iota . \langle \langle P_2 \rangle \rangle_a)$

 a_2

χ

χ

W

L

D

χ

a

W

χ

D

L

D

D

Representing Programs as Mazes $\langle \langle (s^+?!a | !s) \setminus s | s^+?!b \rangle \rangle$



Representing Programs as Mazes $\langle \langle (s^+?!a | !s) \setminus s | s^+?!b \rangle \rangle$





$$s_{2}^{+}?(!s_{1}) | x^{+}?(!s_{1}) | s_{1}^{-}?(!s_{2}) | s_{3}^{+}?(!s_{2}) | x^{-}?s_{2}^{+}?(!s_{3})$$















$$s_{2}^{+}?(!s_{1}) | x^{+}?(!s_{1}) | s_{1}^{-}?(!s_{2}) | s_{3}^{+}?(!s_{2}) | x^{-}?s_{2}^{+}?(!s_{3})$$







$$\Rightarrow \begin{vmatrix} s_1 = s_2 + x \\ s_2 = \overline{s_1} + s_3 \\ s_3 = \overline{x} \cdot s_2 \end{vmatrix} \Rightarrow$$

$$s_{2}^{+?}(!s_{1}) | x^{+?}(!s_{1}) | s_{1}^{-?}(!s_{2}) |$$

 $s_{3}^{+?}(!s_{2}) | x^{-?}s_{2}^{+?}(!s_{3})$





$$\rightarrow \begin{vmatrix} s_1 = s_2 + x \\ s_2 = \overline{s_1} + s_3 \\ s_3 = \overline{x} \cdot s_2 \end{vmatrix} \xrightarrow{\rightarrow} s_2^{+?}(!s_1) \mid x^{+?}(!s_1) \mid s_1^{-?}(!s_2) \mid s_1^{-?}(!s_2) \mid s_3^{+?}(!s_2) \mid x^{-?}s_2^{+?}(!s_3) \end{vmatrix}$$

$$s_{2} = \overline{(s_{2} + x)} + (\overline{x} \cdot s_{2})$$

$$s_{2} = (\overline{s_{2}} \cdot \overline{x}) + (\overline{x} \cdot s_{2})$$

$$s_{2} = \overline{x} \cdot (\overline{s_{2}} + s_{2}) = \overline{x}$$






























Is Timing Analysis a Refinement of Causality Analysis?

Timed Esterel Games are computationally equivalent to Timed Ternary Simulation.

Timing Analysis = Causality Analysis + Time?

Because Mazes are logic specifications of execution schedules that can be used together with time information.

What is WCRT anyway?

It is the **minimal** upper bound on the reaction time.

By definition WCRT determines **exact** timing.

$$WCRT_{1} = \min\{t \mid \exists \alpha. \forall h. \forall s \ge t. h(s) = \alpha\}$$
$$WCRT_{2} = \min\{t \mid \forall h. \exists \alpha. \forall s \ge t. h(s) = \alpha\}$$
$$WCRT_{3} = \min\{t \mid \forall h. \exists \alpha. \text{ if } h \text{ stabilises}$$
$$\Rightarrow \forall s \ge t. h(s) = \alpha\}$$

What is WCRT anyway?

MUST prove that a WCRT algorithm delivers exact results.

But with respect to what model (abstraction)?

Mazes are flexible structures that allows us to consider different levels of atomicity, constraints on the schedule, etc.

What is WCRT anyway?

WCRT no schedule takes more time, this requires/involves causality. It is neither simpler, in principle, nor more difficult than causality analysis.

However, Causality/combinational property depends on level of abstraction & atomicity of scheduling, scheduling model (concurrent, multithreading, ...)

HERE: Esterel-style WCRT concurrent, non-inertial delays ("Chaos" [Burch'92]) algorithms based on maze games.